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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.	
09/164,624	10/01/1998	YOSHIHIRO ISHIDA	35.C-13000	6892	
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FITZPATRICK CELLA HARPER & SCINTO 30 ROCKEFELLER PLAZA			YE, LIN		
	NEW YORK, NY 10112		ART UNIT	PAPER NUMBER	
			2615		
			DATE MAILED: 04/29/2005	5	

Please find below and/or attached an Office communication concerning this application or proceeding.

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	Application No.	Applicant(s)			
	09/164,624	ISHIDA ET AL.			
Office Action Summary	Examiner	Art Unit			
	Lin Ye	2615			
The MAILING DATE of this communication app Period for Reply	ears on the cover sheet with the c	orrespondence address			
A SHORTENED STATUTORY PERIOD FOR REPLY THE MAILING DATE OF THIS COMMUNICATION. - Extensions of time may be available under the provisions of 37 CFR 1.13 after SIX (6) MONTHS from the mailing date of this communication. - If the period for reply specified above is less than thirty (30) days, a reply - If NO period for reply is specified above, the maximum statutory period w - Failure to reply within the set or extended period for reply will, by statute, Any reply received by the Office later than three months after the mailing earned patent term adjustment. See 37 CFR 1.704(b).	36(a). In no event, however, may a reply be time within the statutory minimum of thirty (30) day, will apply and will expire SIX (6) MONTHS from cause the application to become ABANDONF	nely filed s will be considered timely. the mailing date of this communication. D (35 U.S.C. & 133)			
Status					
Responsive to communication(s) filed on 22 De This action is FINAL. 2b) ☐ This Since this application is in condition for allowant closed in accordance with the practice under E	action is non-final. nce except for formal matters, pro				
Disposition of Claims					
4) Claim(s) 24-41 is/are pending in the application 4a) Of the above claim(s) is/are withdraw 5) Claim(s) is/are allowed. 6) Claim(s) 24-41 is/are rejected. 7) Claim(s) is/are objected to. 8) Claim(s) are subject to restriction and/or	vn from consideration.	;			
Application Papers					
9)☐ The specification is objected to by the Examiner 10)☒ The drawing(s) filed on <u>01 October 1998</u> is/are: Applicant may not request that any objection to the o Replacement drawing sheet(s) including the correction 11)☐ The oath or declaration is objected to by the Examiner	a)⊠ accepted or b)⊡ objected drawing(s) be held in abeyance. See on is required if the drawing(s) is obj	e 37 CFR 1.85(a). ected to. See 37 CFR 1.121(d).			
Priority under 35 U.S.C. § 119					
12) Acknowledgment is made of a claim for foreign priority under 35 U.S.C. § 119(a)-(d) or (f). a) All b) Some * c) None of: 1. Certified copies of the priority documents have been received. 2. Certified copies of the priority documents have been received in Application No 3. Copies of the certified copies of the priority documents have been received in this National Stage application from the International Bureau (PCT Rule 17.2(a)). * See the attached detailed Office action for a list of the certified copies not received.					
Attachment(s) 1) \(\int \) Notice of References Cited (PTO-892) 2) \(\sum \) Notice of Draftsperson's Patent Drawing Review (PTO-948) 3) \(\int \) Information Disclosure Statement(s) (PTO-1449 or PTO/SB/08) Paper No(s)/Mail Date \(\frac{7/7/04}{2} \).	4) Interview Summary (Paper No(s)/Mail Da 5) Notice of Informal Pa 6) Other:				

DETAILED ACTION

Response to Arguments

1. Applicant's arguments with respect to claims 24-41 filed on 12/22/04 have been considered but are most in view of the new ground(s) of rejection. Since a new ground of rejection is being applied against previous allowed claims, this action is not made final.

Claim Rejections - 35 USC § 102

2. The following is a quotation of the appropriate paragraphs of 35 U.S.C. 102 that form the basis for the rejections under this section made in this Office action:

A person shall be entitled to a patent unless -

- (b) the invention was patented or described in a printed publication in this or a foreign country or in public use or on sale in this country, more than one year prior to the date of application for patent in the United States.
- 3. Claims 24-25, 31-32, 37-38 and 41 rejected under 35 U.S.C. 102(b) as being anticipated by Paff U.S. Patent 5,164,827.

Referring to claim 24, the Paff reference discloses in Figures 1 -6, an image processing apparatus (any one of the slave cameras SD1-SD5 is considered as the image processing apparatus) comprising: an input unit (image and lens assembly 17, each of slave cameras SD1-SD5 has the same component configuration as the master camera MD, see Col. 3, lines 29-30 and Col. 3, lines 58-62) adapted to input image data; a reception unit adapted to

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receive information of a distance to the object, for detecting a desired object, form an external apparatus that is not part of said image processing apparatus (the master camera MD and monitoring station 11 are considered as the "external apparatus"; the master camera broadcasts the coordinate position of the object S and a desired range value as the "information of a distance to the object" to any one of slave cameras SD1-SD5, see Col. 6, lines 56-60), via a communication interface (bidirectional communications paths 21, see Col. 3, lines 25-27); a detection unit adapted to detect the desired object corresponding to the information received by said reception unit (e.g., the slave camera SD2 first determines the distance between its projected position in plane 2 and the received coordinate position in the plane 2 of the desired object for detecting the distance DSD2 between the slave camera SD2 and the object S, see Col. 6, lines 62-65 and Col. 7, lines 1-9), from the image data input by said input unit and a transmission unit adapted as shown in Figure 5, in a case in which said detection unit detects the desired object, to transmit information reflecting detection of the desired object to the external apparatus via the communication interface (and if distance from a slave camera 2 to the desired object S is determined to be within the desired range, i.e., a radius of 30 feet, the slave camera SD2 will adjust its pan, tilt and zoom status, see Col. 7, lines 10-16; and the slave camera SD2 will reflecting detection of the desired object to the monitor station 11 for displaying the image of desired object on the monitors via the communication interface 21; otherwise if out of the desired range, the slave camera SD2 will not reflecting detection of the desired object to monitor station 11, see Col. 7, lines 54-66).

Referring to claim 25, the Paff reference discloses wherein said input unit of video slave camera SD comprises an image pickup unit (17, each of slave cameras SD1-SD5 has the same component configuration as the master camera MD, see Col. 3, lines 29-30 and Col. 3, lines 58-62) adapted to pick up the object image through an optical system.

Referring to claim 31, the Paff reference discloses all subject matter as discussed with respected to same comment as with claim 24.

Referring to claim 32, the Paff reference discloses all subject matter as discussed with respected to same comment as with claim 25.

Referring to claim 37, the Paff reference discloses in Figures 1 -6, an terminal apparatus (any one of the slave cameras SD1-SD5 is considered as the terminal apparatus) comprising: an input unit (image and lens assembly 17, each of slave cameras SD1-SD5 has the same component configuration as the master camera MD, see Col. 3, lines 29-30 and Col. 3, lines 58-62) adapted to input image data; a reception unit adapted to receive information of a distance to the object, for detecting a desired object, form an external apparatus that is not part of said terminal apparatus (the master camera MD and monitoring station 11 are considered as the "external apparatus"; the master camera **broadcasts** the coordinate position of the object S and a desired range value as the "information of a distance to the object" to any one of slave cameras SD1-SD5, see Col. 6, lines 56-60), via a communication interface (bidirectional communications paths 21, see Col. 3, lines 25-27); a detection unit adapted to detect the desired object corresponding to the information received by said reception unit (e.g., the slave camera SD2 first determines the distance between its projected position in plane 2 and the **received coordinate position** in the plane 2 of the desired object

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for detecting the distance DsD2 between the slave camera SD2 and the object S, see Col. 6, lines 62-65 and Col. 7, lines 1-9), from the image data input by said input unit and a transmission unit adapted as shown in Figure 5, in a case in which said detection unit detects the desired object, to transmit information reflecting detection of the desired object to the external apparatus via the communication interface (and if distance from a slave camera 2 to the desired object S is determined to be within **the desired range**, i.e., a radius of 30 feet, the slave camera SD2 will adjust its pan, tilt and zoom status, see Col. 7, lines 10-16; and the slave camera SD2 will reflecting detection of the desired object to the monitor station 11 for displaying the image of desired object on the monitors via the communication interface 21; otherwise if out of **the desired range**, the slave camera SD2 will not reflecting detection of the desired object to monitor station 11, see Col. 7, lines 54-66).

Referring to claim 38, the Paff reference discloses all subject matter as discussed with respected to same comment as with claims 25 and 37.

Referring to claim 41, the Paff reference discloses all subject matter as discussed with respected to same comment as with claim 37.

Claim Rejections - 35 USC § 103

- 4. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:
 - (a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negatived by the manner in which the invention was made.

5. Claims 26, 27,30, 33-34 and 39-40 are rejected under 35 U.S.C. 103(a) as being unpatentable

over Paff U.S. Patent 5,164,827 in view of Salvati U.S. Patent 6,359,644.

Referring to claim 26, the Paff reference discloses all subject matter as discussed with respected to claim 25, but except Ito does not states the surveillance camera system can use focusing control information to measure the distance from the object to the predetermined position instead of the coordinates of the selected position in the reference plane 2.

The Salvati reference discloses in Figure 2, a video camera (10) comprises a lens system having selected optical characteristics and a CCD imager. The system includes a microprocessor/CPU that calculates the size of the target object by mathematically manipulating the optical characteristics, the focus data, the zoom data, and pixel data. The exact object distance is determined by feedback from the focus motor and calculating the deviation from zero. (See Col. 5, lines 25-30). This would be an advantage over the Paff's surveillance camera system in that it could achieve to change an object image into a distance image for the purpose of recognizing objects and get more accurate distance result as taught by Salvati. For that reason, it would have been obvious to one of ordinary skill in the art at the time to see the surveillance camera can associate the focusing control information for measuring the distance from the detected object to the predetermined position disclosed by Paff.

Referring to claim 27, the Paff and Salvati references disclose all subject matter as discussed with respected to claim 26, and the Salvati reference discloses wherein the image pickup unit comprises a zoom control unit adapted to control zooming of the optical system,

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and said detection unit detects the object according to zoom control information generated by the zoom control unit (e.g., The Salvati's system includes a microprocessor/CPU that calculates the size and distance of the target object by mathematically manipulating the focus data, the zoom data. The exact object distance is determined by feedback from the focus motor and calculating the deviation from zero and the magnification factor M is determined by the position of the zoom servo-feedbacks 17, see Col. 5, lines 25-30).

Referring to claim 30, the Paff and Salvati references disclose all subject matter as discussed with respected to claim 26, and the Paff reference discloses wherein said image processing apparatus is used in a monitoring camera system (video surveillance system, See Col. 1, lines 5-10).

Referring to claim 33, the Paff and Salvati references disclose all subject matter as discussed with respected to same comment as with claims 26 and 31-32.

Referring to claim 34, the Paff and Salvati references disclose all subject matter as discussed with respected to same comment as with claims 27 and 31-32.

Referring to claim 39, the Paff and Salvati references disclose all subject matter as discussed with respected to same comment as with claims 26 and 37-38.

Referring to claim 40, the Paff and Salvati references disclose all subject matter as discussed with respected to same comment as with claims 27 and 37-38.

Claims 28-29, 35-36 are rejected under 35 U.S.C. 103(a) as being unpatentable over Paff
 U.S. Patent 5,164,827 in view of Karmann et al. U.S. Patent 5,034,986.

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Referring to claim 28, the Paff reference discloses all subject matter as discussed with respected to claim 24, but except the Paff reference does not explicitly states the detection unit of slave cameras detects the object according to a difference value between pictures instead that master broadcast the coordinate position of the object.

The Karmann reference teaches in Figures 1-2, a detecting and tracking moving object system calculating a sequence of binary object masks by binarization of a difference image sequence formed from the input image sequence and the background image sequence using a threshold and determining the positions and size of the binary object (See Col. 3, lines 13-18 and lines 23-25). The Fujioka reference is evidenced that one of ordinary skill in the art at the time of the invention to see more advantages for the image processing apparatus can detect the moving object according to a difference value between pictures so that the apparatus can quickly track and determine the position of desired object without waiting for external input. For that reason, it would have been obvious to modify the system of Paff by providing the detection unit of slave cameras detects the object according to a difference value between pictures as taught by Fujioka.

Referring to claim 29, the Paff and Karmann references disclose all subject matter as discussed with respected to claim 28, and the Karmann reference discloses wherein said detection unit binarizes the difference value by using a predetermined threshold and detects the object according to a binarization result (See Col. 3, lines 13-18 and Col. 4, lines 34-42).

Referring to claim 35, the Paff and Karmann references disclose all subject matter as discussed with respected to same comment as with claim 28.

Referring to claim 36, the Paff and Karmann references disclose all subject matter as discussed with respected to same comment as with claim 29.

Conclusion

- 7. The prior art made of record and not relied upon is considered pertinent to applicant's disclosure.
 - a. Fujioka et al. U.S 4,908,704 discloses an apparatus for monitoring a moving object.
 - b. Blackshear U.S. 5,111,288 discloses a surveillance camera system comprises housing and board computer with a joystick and control unit for issuing instructions to the computer.
 - c. Ito et al. U.S. 6,108,033 discloses a difference between an input image including images of a background image picked up by an image pick-up unit.
- 8. Any inquiry concerning this communication or earlier communications from the examiner should be directed to Lin Ye whose telephone number is (571) 272-7372. The examiner can normally be reached on Mon-Fri 8:00AM-5:00PM.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, James J. Groody can be reached on (571) 272-7950. The fax phone number for the organization where this application or proceeding is assigned is 703-872-9306.

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to the Private PAIR system, contact the Electronic Business Center (EBC) at 866-217-9197

(toll-free).

Lin Ye April 26, 2005 James J. Groody Supervisory Patent Examiner

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